

2019 INCOSE SD Mini Conference

# #RoboSub Influencer 2020 - Inspiring the Next Generation of Systems Engineers

November 2, 2019

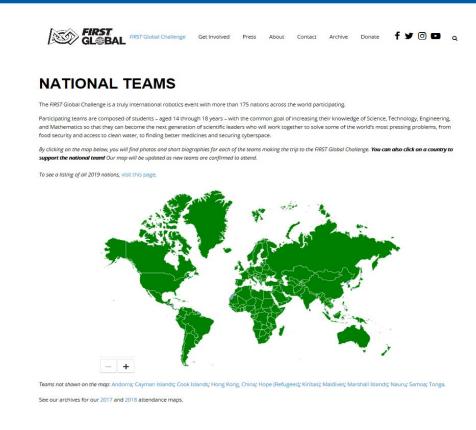
Mabel Szeto, Colin Szeto Team Inspiration



#### About Team Inspiration



- Team Inspiration's Mission
  - To Learn, To Share, To Innovate, To Inspire
- Robotics Involvement
  - Learning robotics since 3<sup>rd</sup> grade
  - Compete in FLL, FTC, Robocar and RoboSub
  - Host robotics events in local communities since 2012
  - Host robotics events in global communities in 2019
  - Advisory team for FIRST Global
- STEM teaching since 2017
  - Weeklong robotics camp
  - Guide local/global robotics teams and coaches
  - On average, weekly STEM teaching



#### FIRST Global 2019 nations

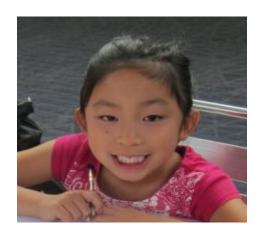
Contributor of Mentor Guide for *FIRST* Global, 175 nations Coach Teams Benin, Bolivia, Paraguay and Togo

#### Vision & Reflection



- Team members have observed RoboSub competitions since 2011
- Reflection and close observation occur in every stage of the life cycle from concept development to final <u>competition</u>





Program robots in 3<sup>rd</sup> grade - 2011



Photo taken in 2017

# Systems Engineering "V" is an Enabler



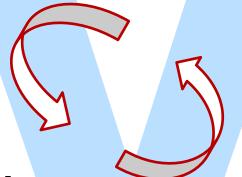
**Competitor Research, Industry Survey** 

**Mission Exploration** 

**Planning** 

**Requirement Development** 

**Self-Awareness** 



Reflection

**System Testing** 

**Subsystem Testing** 

**Component Testing** 

**Design Review** 

Modular & Parallel Development

Best practice with focus on reflection and self-awareness

## Competitors Research & Industry Survey



#### Learn from competitors

- Survey RoboSub teams from last five years
- Identify equipment usage
- Identify lessons learned
- Ask for advice
- Study their subs
- Learn from industry professionals
- Systems engineering process proven at TRW, NASA JPL, Northrop Grumman
- Marine industry products
- Interview professional from Scripps Institute of Oceanography

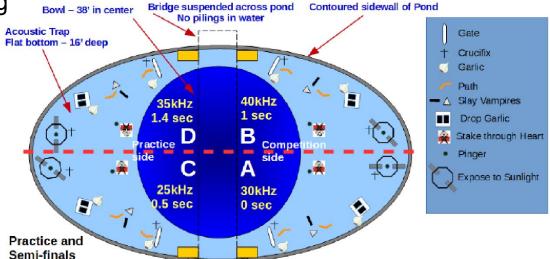


## Mission Exploration



- Understand objectives and rules of engagement
  - Fully autonomous
  - Navigation
  - Object recognition
  - Beacon localization
  - Retrieval and deposit of objects
  - Torpedo targeting
  - Time limit

- Paying close attention to team constraints
  - Schedule (20 weeks)
  - Resources (garage lab vs national/university lab)
  - Performance (low cost components vs professional marine grade components)
  - RoboSub knowledge (zero to competitive)





## **Planning**



- Draft schedule at Kick-Off schedule focus
- Develop schedule backward from goal with contingency
- Long lead material procurement RoboSub components
- Rapid prototype weekly increments
- Parallel and modular development
- Early testing start from the beginning
- Multiple decision milestones

Week	Agenda	
16-Mar	Kick off – RoboSub team research	
23-Mar	RoboSub team research – refine requirements – assign role	
30-Mar	Identify/procure long lead items – Select computer – prioritize requirements	
6-Apr	Connect benchtop vehicle – test component	
13-Apr	Identify all equipment	
20-Apr	program remote control	
27-Apr	put together simple underwater vehicle – first prototype	
4-May	Experiment first prototype in water	
11-May	Progam autonomous	
18-May	Experiment with IMU and depth sensor	
25-May	Experiment with computer vision	
1-Jun	Draft technical paper	
8-Jun	Review draft – Experiment with second prototype	
15-Jun	Final technical paper	
22-Jun	Submit technical paper	
29-Jun	Experiment sonar	
6-Jul	Experiment with final vehicle	
	Data correlation with vision input	
13-Jul	Pre-qualification	
20-Jul	Refine autonomous programming	
27-Jul	Pack robot for competition	
Jul 29 - Aug 4	Competition at NIWC PAC TRANSDEC	

#### Requirement Development



- Understand systems requirements
  - Flow down to mechanical, software, test, operation
- Understand interface
  - HW-HW, SW-SW, HW-SW, user
- Prioritize requirements

30%	Team capability
25%	Schedule
20%	Cost
10%	Risk
15%	Performance
100% Weighted	Criteria



#### Self-Awareness



- Team members capabilities and resource
  - Printed circuit card development (knowledge, resource & schedule)
  - FPGA (knowledge, resource & schedule)
  - Artificial Intelligent (knowledge & schedule)
  - Neural network (knowledge & schedule)
  - Machine milling part (cost)
  - Complex sensors (cost & complexity)
  - General robotics knowledge
  - Integration
  - Programming
  - Garage lab and pool
  - Systems engineering
  - Teamwork
  - Dedication
  - Passion and drive
  - Mentors



# Design Review



- Design review is critical to align the team direction and awareness
- Trade study allows better decision making
- Rapid prototyping allows concept validation
- Weekly status review provides valuable feedback



## Modular and Parallel Development



- Modular development allows team members to tackle multiple payload investigation simultaneously
- Parallel breadboard, simple vehicle, remote control vehicle testing allow timely design concept verification to identify development shortfall
  - Lessons learned are incorporated into the final vehicle development
- CAD and 3D printing allow quick modeling and testing of the design







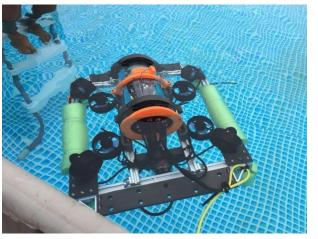
# Testing, Testing, and More Testing



- Breadboard testing starts in the second week is key to shorten the development life cycle
- Remote-control vehicle testing allows observation to incorporate features into the final design
- Incremental testing allows rapid lessons learned
- Early subsystem and system level testing allows us to improve the design and development weekly similar to the agile process









#### Accomplishments



- 2019 International RoboSub Competition (55 of the 59 teams from universities around the world)
  - 5 high school and 9 middle school students
  - 2<sup>nd</sup> in US and 3<sup>rd</sup> in the world for static judging of technical paper, technical presentation, video, and pre-qualification
  - 7<sup>th</sup> in US and 12<sup>th</sup> in the world for overall robot performance
  - Most Inspirational Team award
  - IEEE Innovation award

#### FIRST robotics

- 2017 7<sup>th</sup> ranking in the world robotics championship
- 2018 39<sup>th</sup> ranking in the world robotics championship
- 2019 Winning Alliance and 3<sup>rd</sup> place Inspire in San Diego Regional (state)

#### Robocar

- Multiple awards in local competitions
- Coaches multiple award winning teams and mentors
  - 2017 Team Benin ranked 7<sup>th</sup> in the FIRST Global World competition, 1<sup>st</sup> in Africa
  - 2018 FIRST Global Best Mentor (Team Benin) in the world





FÉLICITATIONS AUX CHAMPIONS

# Keynotes



# Know the mission – understand the problem to solve

Keep It Simple Silly

Passion

Reliability

Teach

Fail quickly

Teamwork



#### Acknowledgement



#### Team Inspiration Members

 Mabel Szeto (Team Captain), Aditya Mavalankar, Ashika Palacharla, Ashiria Goel, Colin Szeto, Eesh Vij, Eric Silberman, Ilan Cosman, Noah Tang, Pahel Srivastava, Raina Shapur, Rishi Veerepalli, Shreyas Rangan, and Shruti Natala

#### Lead coaches

Alex Szeto, Jack Silberman

#### Mentors

Amit Goel, Dave Warner, Eric Lo, Eugene Kim, Kenzo Tomitaka, Kris Chopper, Kunal Srivastava, Lindsay
 Westerfield, Pamela Cosman, Pat McLaughlin, Phil Yao, Michael Arnstein, Valibabu Saladi, and Venkat Rangan

#### Sponsors/supporters

# To Inspire



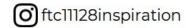






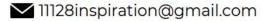
# Join our journey to share your systems engineering knowledge and lessons learned











team11128.wixsite.com/main







# Benin Robotics Training/Competition



- Team Inspiration co-hosted a robotics training/competition in Benin with US Embassy, Team Spyder, femCoders' support
- Our goal is to have STEM classes in every high school in Benin and replicate the success model worldwide
- The event attended by:
  - 13 Benin schools
  - Representatives from Nigeria and Togo
  - Benin Minister of Education, Minister of Economic Development, and US Embassy
    Public Affairs officers







Sharing and teaching are keys to team learning